

The Ohio State University  
Department of Electrical and Computer Engineering

ECE 551

Quiz #3

May 16, 2008

Given the transfer function

$$G(s) = \frac{-(s-10)}{s(s+10)}$$

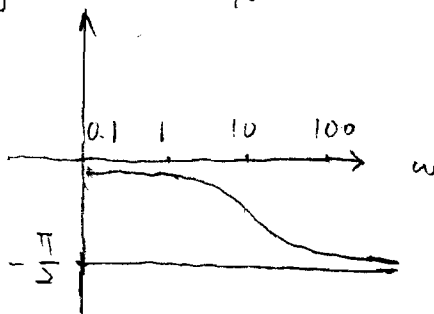
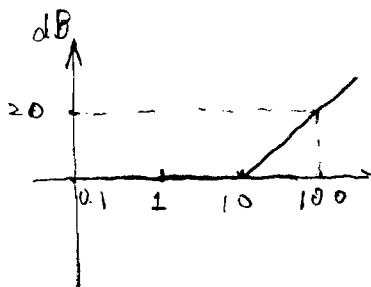
Sketch the Bode magnitude (dB vs log $\omega$  in radians) and phase (degrees vs. log $\omega$  in radians) plots below. You must label each portion of the plot, clearly indicating the final result.

$$G(s) = \frac{10(1 - \frac{1}{10}s)}{10 \cdot s(1 + \frac{1}{10}s)} = \frac{1 - \frac{1}{10}s}{s(1 + \frac{1}{10}s)} \quad G(j\omega) = \frac{1 - j\frac{\omega}{10}}{j\omega(1 + j\frac{\omega}{10})}$$

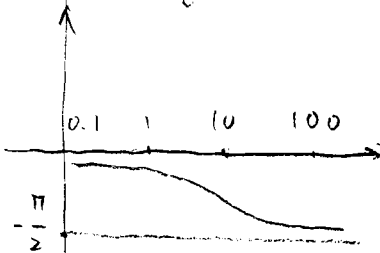
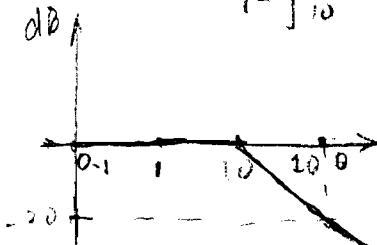
1. For  $G_1(j\omega) = 1 - j\frac{\omega}{10}$

$$20 \lg |G_1(j\omega)| = 20 \lg \sqrt{1 + (\frac{\omega}{10})^2}$$

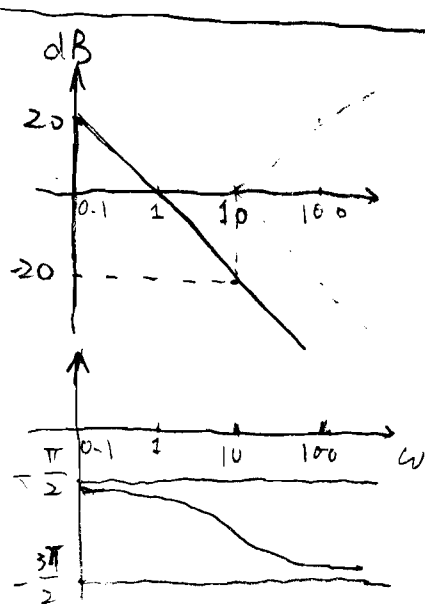
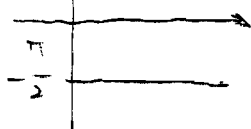
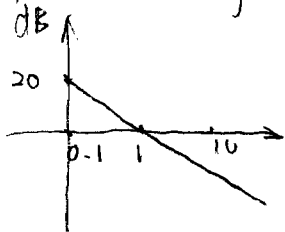
$$\angle G_1(j\omega) = \tan^{-1}(-\frac{\omega}{10}) = -\tan^{-1} \frac{\omega}{10}$$



2. For  $G_2(j\omega) = \frac{1}{1 + j\frac{\omega}{10}}$   $20 \lg |G_2(j\omega)| = -20 \lg \sqrt{1 + (\frac{\omega}{10})^2}$   $\angle G_2(j\omega) = -\tan^{-1} \frac{\omega}{10}$



3. For  $G_3(j\omega) = \frac{1}{j\omega}$   $20 \lg |G_3(j\omega)| = -20 \lg \omega$   $\angle G_3 = -\frac{\pi}{2}$



4.  $G(j\omega) = \frac{1 - j\frac{\omega}{10}}{j\omega(1 + j\frac{\omega}{10})}$

total

# Design Project #1. Solution.

P10.1  $\zeta = 0.6 \Rightarrow p.o. = e^{-\zeta/\sqrt{1-\zeta^2}} \times 100\% = 9.48\%$   
 $t_s < 2.5 \Rightarrow \frac{4}{\zeta \omega_n} < 2.5, \zeta \omega_n > 1.6, \omega_n > 2.67$

Lead Compensator  $G_c(s) = \frac{s+z_c}{s+p_c}, z_c < p_c$

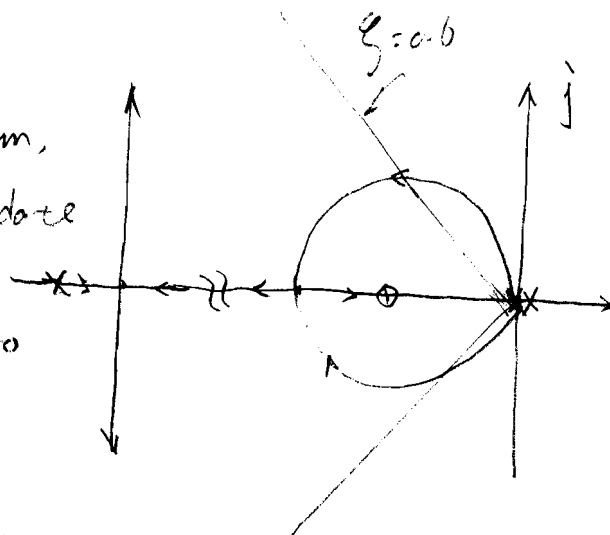
Pick a zero  $z_c$  to drag root locus to LHP, pick a pole for from origin to make root locus move to real axis. Also pick a large  $k$  to ensure that  $\omega_n > 2.67$  to meet overshoot specification.

Since this is a design problem, I can only give one candidate design.

I pick  $k_1 = 1, z_c = 3, p_c = 300$   
 $k_2 = 6300$

$G_c = 6300 \frac{s+3}{s+300}$

overshoot 9.47%,  $t_s = 0.715$ .



P10.3  $G(s) = \frac{16(s+1)}{s(s^2+2s+16)}$ ,  $p.o. < 5\% \Rightarrow \zeta_d > 0.69$   
 $t_s < 5, \zeta \omega_n > 0.8, \omega_n > 1.15$

design strategy is same as 10.1.

Here we also use  $G_c(s) = \frac{k(s+1)}{s+300}$

choose  $k = 2000$ .

$p.o. = 2.35\%, t_s = 1.085$ .

