

Agenda for the 2006 Six Month Review of the

AFRL/VA and AFOSR



Collaborative Center of Control Science (CCCS)

The Ohio State University



Thursday, April 13, 2006

Rooms 259, 260, 267 Dreese Laboratories (For directions, maps, and accommodations see web site: http://www.ece.osu.edu/~passino/cccs.html)

Agenda for the 2006 Six-Month Review

Thursday, April 13, 2006

Cooperative Control for UAVs: Rm. 260 Dreese Laboratories

9:00am	Mobile Sensor Agents Ümit Özgüner
9:45am	Multiple Pursuer/Multiple Evader Problems Dongxu Li and Joe Cruz
10:30am	Break
11:00am	Coordinated Motion for Obstacle Avoidance and Target Capture Shreecharan Kanchanavally, Jingyi Yao, Raúl Ordóñez
11:45am	Discussion
12:00pm	Lunch (catered, on-site)
1:00pm	Stable UAV Distributions for Surveillance Jorge Finke and Kevin Passino
1:45pm	Distributed Coordination Strategies for Wide-Area Patrol Brandon Moore and Kevin Passino
2:30pm	Break
3:00pm	Transitioning Theory to Implementations Keith Redmill and Ümit Özgüner
3:45pm	Demo is planned, discussion (formulations, testbed, etc.)

Control of Reusable Launch Vehicles: Rm. 259 Dreese Laboratories

9:00am Updates on Maneuver Automaton-Based Trajectory Generation on Approach and Landing for RLVs Zhesheng Jiang, Raúl Ordóñez

9:30am Discussion

10:00am	Updates on Control Design for Air-breathing Hypersonic Vehicles David Sigthorsson, Jason Parker, Andrea Serrani
10:45am	Break
11:15am	Updates on Modeling of Air-breathing Hypersonic Vehicles Mike Bolender, Mike Oppenheimer
11:45 am	Discussion
12:15pm	Lunch (catered, on-site)
1:00pm	Discussion

Aerodynamic Flow Control: Rm. 267 Dreese Laboratories

12:00pm	Lunch (catered, on-site)
1:00pm	Introduction & updates Mo Samimy
1:15pm	Air Force interest in flow control James Myatt
1:30pm	Control design status and issues Andrea Serrani
1:45pm	Reduced-order modeling status and issues Chris Camphouse and Edgar Caraballo
2:00pm	Discussion of issues - everyone
3:00pm	Break
3:15pm	Actuator modeling and control Kihwan Kim
3:30pm	Discussion of issues continues - everyone